

Bayesian averaging for ground state masses of atomic nuclei in a Machine Learning approach

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2 ABSTRACT

3 We present global predictions of the ground state mass of atomic nuclei based on a novel
4 Machine Learning (ML) algorithm. We combine precision nuclear experimental measurements
5 together with theoretical predictions of unmeasured nuclei. This hybrid data set is used to train a
6 probabilistic neural network. In addition to training on this data, a physics-based loss function is
7 employed to help refine the solutions. The resultant Bayesian averaged predictions have excellent
8 performance compared to the testing set and come with well-quantified uncertainties which
9 are critical for contemporary scientific applications. We assess extrapolations of the model's
10 predictions and estimate the growth of uncertainties in the region far from measurements.

11 **Keywords:** Atomic Nuclei, Bayesian Averaging, Binding Energies and Masses, Machine Learning - ML, Nuclear Physics, Computational
12 Physics

1 INTRODUCTION

13 Mass is a defining quantity of an atomic nucleus and appears ubiquitously in research efforts ranging from
14 technical applications to scientific studies such as the synthesis of the heavy elements in astrophysical
15 environments [1, 2]. While accurate nuclear data of masses is available for nuclei that are relatively stable,
16 the same is not true for nuclei farther away from beta stability because measurements on radioactive nuclei
17 are exceedingly challenging [3]. As a consequence, theoretical models of atomic nuclei are required for
18 extrapolations used in present-day scientific applications [4].

19 The goal of theoretical nuclear models is to describe all atomic nuclei (from light to heavy) using
20 fundamental interactions. Attainment of this challenging goal remains elusive, however, due to the sheer
21 complexity of modeling many-body systems with Quantum Chromodynamics [5]. To understand the range
22 of nuclei that may exist in nature, mean-field approximations are often made which simplify complex
23 many-body dynamics into a non-interacting system of quasi-particles where remaining residual interactions

24 can be added as perturbations [6]. A consequence of this approximation is that current nuclear modeling
25 efforts are unable to describe the rich correlations that are found across the chart of nuclides.

26 In contrast, Machine Learning (ML) based approaches do not have to rely on the assumption of modeling
27 nuclei from a mean-field. This provides freedom in finding solutions that contemporary modeling may
28 not be capable of ascertaining. Furthermore, Bayesian approaches to ML afford the ability to associate
29 predictions with uncertainties [7, 8]. Such tasks are more difficult to achieve in modern nuclear modeling
30 due to relatively higher computational costs.

31 ML approaches in nuclear physics were pioneered by J.W. Clark and colleagues [9, 10]. These studies
32 were the first to show that networks could approximate stable nuclei, learn to predict masses and analyze
33 nuclear systematics of separation energies as well as spin-parity assignments [11, 12]. Powered by open-
34 source frameworks, research into ML methods has seen a recent resurgence in nuclear physics [13]. ML
35 approaches have shown promise in optimizing data and experiments [14], building surrogate models of
36 density functional theory [15], and describing quantum many-body wave functions for light nuclei [16, 17].

37 Several research groups are actively pursuing the problem of describing nuclear systems with ML from a
38 more data-centric approach. These efforts currently attempt to improve existing nuclear models by adding
39 correction terms [18]. Gaussian Processes (GP) have also been used for model averaging [19], but this
40 approach is inherently limited to where data is known as GP methods typically revert to the mean when
41 extrapolating. A further limitation to training ML models on residuals (or the discrepancy of theoretical
42 model predictions with experimental data) is that the methods are arbitrary. The changes learned by the
43 network to improve one model will not be applicable to another. These approaches thus provide limited
44 insight into the underlying missing physics in modern models of the atomic nucleus.

45 In Lovell et al. [20], a different approach was taken, where the masses of atomic nuclei were modeled
46 directly with a neural network. It was shown that the masses of nuclei can be well described, and model
47 predictions with increased fidelity correlate strongly with a careful selection of physically motivated input
48 features. The selection of input features is especially important in ML applications [21, 22]. Following this
49 work, Mumpower et al. [23] showed that the size of the training set can greatly be reduced, and the fidelity
50 of model solutions increases drastically, when an additional physical constraint is introduced as a second
51 loss function during model training.

52 The focus of this work is to present a Bayesian approach for combining precision data with theoretical
53 predictions to model the mass of atomic nuclei. In Section 2, we present our ML algorithm and define the
54 model hyperparameters. In Section 3, we show the results of our approach and assess the quality of model
55 extrapolations. We end with a short summary.

2 METHODS

56 In this section, we outline our methodology: describe the neural network, define our physics-based feature
57 space, list model hyperparameters, and discuss training.

58 2.1 Mixture Density Network

59 In a feed-forward neural network, inputs, \mathbf{x} , are mapped to outputs, \mathbf{y} , in a deterministic manner. We
60 employ the Mixture Density Network (MDN) of Bishop [24] which differs from the standard approach.
61 This ML network takes as inputs stochastic realizations of probability distributions and maps this to a
62 mixture of Gaussians. Thus, the network fundamentally respects the probabilistic nature of both known

63 data and model predictions by both sampling the prior distribution of inputs and predicting the posterior
64 distribution of the outputs.

65 Formally, the conditional probability can be written as

$$p(\mathbf{y}|\mathbf{x}) = \sum_{i=1}^K \pi_i(\mathbf{x}) \mathcal{N}(\mathbf{y}|\mu_i(\mathbf{x}), I\sigma_i(\mathbf{x})) , \quad (1)$$

66 where \mathcal{N} is the normal distribution with means, $\mu_i(\mathbf{x})$, and standard deviations, $\sigma_i(\mathbf{x})$. The $\pi_i(\mathbf{x})$ represent
67 the weighting of each Gaussian respectively. The covariance matrix is assumed to be diagonal, as indicated
68 by the use of the notation $I\sigma_i$.

69 The neural network outputs are π , μ , and σ which depend only on the input training set information \mathbf{x}
70 and the network weights. For ease of reading the equation we have kept the dependence of the network
71 weights implicit.

72 The hyperbolic tangent function $a(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$ is used as the activation function for the neurons in the
73 linear layers of the network. At the final layer a softmax function is used for the π_i so that the previous
74 layer's output can be mapped to a vector that sums to unity. This choice ensures that the mixture of
75 Gaussians can be safely interpreted as a probability. Our MDN uses the PyTorch Paszke et al. [25]
76 framework and can be run on either CPU or GPU architectures.

77 2.2 Physics-based feature space

78 We now discuss the components of the input vector, \mathbf{x} . The ground state of an atomic nucleus comprises
79 Z protons and N neutrons. While it is reasonable to start from these two independent features as inputs,
80 [21] and Lovell et al. [20] reported that a modestly larger physics-based feature space drastically improves
81 the prediction of masses. For this reason, we employ a combination of macroscopic and microscopic
82 features that are of relevance to low-energy nuclear physics properties.

83 In addition to the proton number Z and neutron number N , we also use the mass number $A = Z + N$,
84 and a measure of isospin asymmetry, $P_{\text{asym}} = \frac{N-Z}{A}$, as relevant macroscopic features. For the microscopic
85 features that encode the quantized nature of atomic nuclei, we employ notions of pairing by considering
86 the even-odd behavior of the proton, neutron, and mass numbers. This can be calculated by observing the
87 binary values of these quantities modulo 2; $Z_{\text{eo}} = Z \div 2$, $N_{\text{eo}} = N \div 2$, $A_{\text{eo}} = A \div 2$. A notion of shell
88 structure is also important. To encode this information we include the number of valence nucleons or holes
89 (beyond the mid-shell) from the nearest major closed shell for protons, V_p , and neutrons, V_n , respectively.
90 The value of V_p or V_n is zero at a closed shell and reaches a maximum at the mid-shell. The number of
91 valence nucleons is correlated with more complex excitations in nuclei, including collective behavior that
92 may appear [26, 27]. The closed proton shells are set to 8, 20, 28, 50, 82, and 114. The closed neutron
93 shells are set to 8, 20, 28, 50, 82, 126 and 184. These choices are free parameters in our modeling and can
94 be modified to explore different physics.

95 The input feature space is then a nine component vector:

$$\mathbf{x} = (Z, N, A, P_{\text{asym}}, Z_{\text{eo}}, N_{\text{eo}}, A_{\text{eo}}, V_p, V_n) , \quad (2)$$

96 where the first four components can be considered macroscopic features and the last five are microscopic
97 features. All remaining features beyond the second are functions of Z and N exclusively.

98 2.3 Hybrid data for training

99 Our training is hybrid data consisting of two distinct input sets. The first is the mass data provided by the
100 2020 Atomic Mass Evaluation (AME2020) [28]. The information in this set is very precise with an average
101 reported mass uncertainty of roughly 25 keV. Modern experimental advances, such as Penning trap mass
102 spectrometers enhanced with the Phase-Imaging Ion-Cyclotron-Resonance technique, enable such high
103 precision measurements [29, 30].

104 The second mass data are provided by modern theoretical models. The information in this set is less
105 precise, owing to the approximations made in the modeling of atomic nuclei. This set can be calculated for
106 nuclei that have not yet been measured, providing a valuable new source of information. Nuclear models in
107 this second set include macroscopic-microscopic approaches like the Duflo-Zuker model [31], the 2012
108 version of the Finite Range Droplet Model (FRDM) [32], the WS4 model [33] and microscopic approaches
109 like UNEDF [34], and HFB32 [35].

110 In this work, we combine predictions from three theoretical models: FRDM2012, WS4, and HFB32.
111 Because these models do not report individual uncertainties on their predictions, we instead estimate
112 theoretical model uncertainty using the commonly quoted root-mean-square error or

$$\sigma_{\text{RMS}} = \sqrt{\frac{1}{N} \sum_j^N (d_j - t_j)^2}, \quad (3)$$

113 where d_j is the atomic mass from the AME and t_j is the predicted atomic mass from the theoretical model.
114 The sum runs over each j which defines a nucleus, (Z, N) . For FRDM2012, WS4, and HFB32, $\sigma_{\text{RMS}} =$
115 0.606, 0.295 and 0.608 MeV respectively, using AME2020 masses. While the σ_{RMS} is a good measure of
116 overall model accuracy for measured nuclei, uncertainties are certainly larger for shorter-lived systems.
117 In this work, we do not seek to preferentiate one model over another. For this reason, we increase the
118 assumed uncertainty of WS4 to a more reasonable 0.500 MeV when probing its predicted masses further
119 from stability.

120 Training for the hybrid input data is taken at random, rather than selected based on any given criteria. The
121 number of unique nuclei from experimental data is a free parameter in our training. The best performance
122 is found for models provided with approximately 20% of the AME, or 400 to 500 nuclei [23]. The number
123 of unique nuclei from theory is also a free parameter. We find that as few as 50 additional unmeasured
124 nuclei can influence training, and therefore use this minimal number. In the case of theory data, we sample
125 the masses of 50 randomly chosen nuclei from each of the three mass models independently.

126 The benefit of using hybrid data is that the neural network is not limited to solutions of model averaging
127 which can regress to the mean when extrapolating. Instead, the combination of hybrid data with ML-based
128 methods affords the opportunity to create new models that are capable of reproducing data, capturing
129 trends, and predicting yet to be measured masses with sound uncertainties.

130 2.4 Model training and hyperparameters

131 The network is set up with 6 hidden layers and 10 hidden nodes per layer. The final layer turns the
132 network into a Gaussian ad-mixture. For masses we choose a single Gaussian, although other physical
133 quantities, such as fission yields, may require additional components [36]. The Adam optimizer is used
134 with learning rate 0.0002 [37]. We also implement a weight-decay regularization with value 0.01. These
135 hyperparameters were determined from a select set of runs where the values were varied.

136 We perform model training with two loss functions. The first loss function, \mathcal{L}_1 , captures the match to
 137 input data. The log-likelihood loss for data is written as,

$$\mathcal{L}_1 = -\ln \left[\sum_{i=1}^K \frac{\pi_i(\mathbf{x})}{(2\pi)^{K/2} \sigma_i(\mathbf{x})} \exp \left\{ -\frac{\|\mathbf{y} - \mu_i(\mathbf{x})\|^2}{2\sigma_i(\mathbf{x})^2} \right\} \right], \quad (4)$$

138 where \mathbf{y} is the vector of training outputs and K is the total number of Gaussian mixtures. The $\pi_i(\mathbf{x})$, $\mu_i(\mathbf{x})$,
 139 and $\sigma_i(\mathbf{x})$, variables define the Gaussians, as in Eqn. 1. The minimization of this loss function furnishes the
 140 posterior distributions of predicted masses.

141 The hybrid mixture of experimental data and theoretical data enter into training as the variable \mathbf{y} . Each
 142 nucleus defined uniquely by a proton number Z and neutron number N . A Gaussian distribution is assumed
 143 to represent the probability distribution for sampling both experimental and theoretical data,

$$f(y, \mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \exp \left(-\frac{1}{2} \left(\frac{y - \mu}{\sigma} \right)^2 \right). \quad (5)$$

144 For the high-precision experimental data taken from the AME, the mean is set to the evaluated mass,
 145 $\mu = M_{Z,N}^{\text{AME}}$, and the variance is set to the reported uncertainty of a nucleus' mass, $\sigma = \delta M_{Z,N}^{\text{AME}}$. For the
 146 theoretical data from the three mass models, the mean value is taken as the prediction of the given mass
 147 model respectively. The uncertainties in these models is not reported on a per nucleus basis. Therefore an
 148 approximation to the model's σ_{RMS} , which is computed with respect to the AME, is used as the variance in
 149 the probability distribution.

150 In this work, we do not include masses of isomeric states in the training set. However, we note that since
 151 our previous works [20, 23], the AME2020 is now utilized, rather than the earlier AME2016. This data
 152 better refines the separation of ground state and isomeric states in evaluated masses, which continues to be
 153 a known source of systematic uncertainty in the evaluation of atomic masses.

154 For the AME data, we take roughly 500 nuclei for training, leaving the remaining 80% of the AME as
 155 testing data. The number of stochastic realizations per nucleus is 50. For theory data, we take only 50
 156 additional nuclei explicitly outside the AME. These nuclei are also taken at random. A given nucleus is set
 157 to have 20 stochastic realizations per theory model, for a total of 60 samples overall. From a set of testing
 158 runs, the above choices produce suitable models. We summarize the model hyperparameters in Table 1. A
 159 more complete study of all model hyperparameters is the subject of future investigations.

160 One essential observation of ground-state masses is that they obey the eponymous Garvey-Kelson (GK)
 161 relations [38]. This result suggests a judicious choice of mass differences of neighboring nuclei that
 162 minimizes the interactions between nucleons to first order, resulting in particular linear combinations that
 163 strategically sum to zero.

164 If $N \geq Z$, the GK relations state that the mass difference is

$$\begin{aligned} &M_{Z-2,N+2} - M_{Z,N} + M_{Z-1,N} \\ &- M_{Z-2,N+1} + M_{Z,N+1} - M_{Z-1,N+2} \approx 0, \end{aligned} \quad (6)$$

Table 1. The neural network hyperparameters used in this work.

| Parameter | Value(s) | Comment |
|---------------------------------|-----------------------------|--|
| λ_{layers} | 6 | Defines the number of hidden layers. |
| λ_{nodes} | 10 | Defines the number of hidden nodes per hidden layer. |
| λ_{gauss} | 1 | Defines the number of Gaussians used in the MDN. |
| λ_{lr} | 0.0002 | Defines the learning rate of the Adam optimizer. |
| λ_{wd} | 0.01 | Defines the weight-decay regularization. |
| λ_{exp} | 506 | Defines the number of AME2020 data used in training. |
| $\lambda_{\text{exp-pulls}}$ | 50 | Defines the number of samples per AME mass. |
| λ_{theory} | 50 | Defines the unique nuclei probed using the three models. |
| $\lambda_{\text{theory-pulls}}$ | 20 | Defines the number of samples per theory mass. |
| λ_{physics} | 1.0 | Defines the strength of the physics loss enforcement. |
| $\lambda_{\text{Z-low}}$ | 5 | Defines the minimal proton number for the network. |
| $\lambda_{\text{N-shells}}$ | 8, 20, 28, 50, 82, 126, 184 | Defines the major closed neutron shells. |
| $\lambda_{\text{Z-shells}}$ | 8, 20, 28, 50, 82, 114 | Defines the major closed proton shells. |
| $\lambda_{\text{FRDM2012}}$ | 0.6 MeV | Defines the uncertainty used in probing FRDM2012 masses. |
| λ_{WS4} | 0.5 MeV | Defines the uncertainty used in probing WS4 masses. |
| λ_{HFB32} | 0.6 MeV | Defines the uncertainty used in probing HFB32 masses. |

165 and for $N < Z$,

$$M_{Z+2,N-2} - M_{Z,N} + M_{Z,N-1} - M_{Z+1,N-2} + M_{Z+1,N} - M_{Z+2,N-1} \approx 0. \quad (7)$$

166 Higher order GK mass relations may also be considered, as in Ref. Barea et al. [39]. However, the use
 167 of these constraints alone does not yield viable predictions far from stability due to the accumulation of
 168 uncertainty as the relationship is recursively applied beyond known data [40].

169 As an alternative, we perform no such iteration in our application of the GK relations. Equations 6 and 7
 170 are used directly, and it is important to recognize that these equations depend exclusively on the masses.
 171 Thus the second (physics-based) loss function can be defined purely as a function of the ML model's mass
 172 predictions.

173 To enforce this physics-based observation, the second loss function can be defined as

$$\mathcal{L}_2 = -\ln \left(\left| \sum_{\{C\}} GK(\boldsymbol{\mu}) \right| \right), \quad (8)$$

174 where GK is function that defines the left-hand side of Equations 6 and 7 and we only use the model's
 175 predicted mean value of the masses, $\boldsymbol{\mu}$. The sum is performed over any choice of subset, $\{C\}$, of masses
 176 and does not have to overlap with the hybrid training data. The absolute value is necessary to ensure that
 177 the log-loss remains a real number. As with the data loss, \mathcal{L}_1 , we also seek to simultaneously minimize the
 178 physics-loss, \mathcal{L}_2 , which amounts to reducing the error among the difference in masses defined in the above
 179 equations.

180 An alternative to Equation 8 that is potentially more restrictive, is to take the absolute value inside the
 181 summation

$$\mathcal{L}_2^{\text{alt}} = -\ln \left(\sum_{\{C\}} |GK(\boldsymbol{\mu})| \right). \quad (9)$$

182 Because Equation 9 sums many non-zero items, it is a larger loss than using Equation 8. In this case, the
 183 strength of the physics hyperparameter (discussed below) should generally be lower than in the case of
 184 using Equation 8. A strong preference for selecting one functional form for the physics-based loss over the
 185 other has not been found.

186 The total loss function used in training is taken as a sum of the data and physics losses

$$\mathcal{L}_{\text{total}} = \mathcal{L}_1 + \lambda_{\text{physics}}\mathcal{L}_2 \quad (10)$$

187 where λ_{physics} is a model hyperparameter which defines the strength of enforcement of the physics loss. We
 188 have found that values between 0.1 and 2 generally enforce the physics constraint in model predictions.

189 2.5 Assembling a model

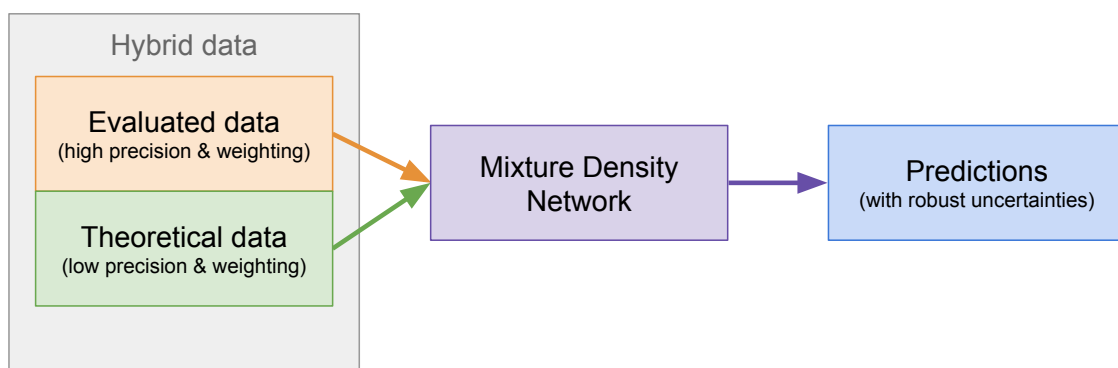


Figure 1. A schematic of our methodology. The procedure used in this work combines high precision evaluated data with a handful of less-precise theoretical data. This results in predictions with well-quantified uncertainties across the chart of nuclides.

190 A schematic of our methodology is shown in Figure 1 and encapsulated below. The modeling of masses
 191 begins by setting hyperparameters, summarized in Table 1, for the particular calculation. A random
 192 selection of hybrid data is made, as can be seen in Figure 2. The bulk of the masses selected for training
 193 comes from the AME (black squares) where high-precision evaluated data resides (gray squares). Only a
 194 handful of masses from theoretical models are taken for training (red squares).

195 After selection of hyperparameters and data, training begins which seeks to minimize the total loss,
 196 Eqn. 10. Training can take many epochs, and the data loss as well as the physics loss play important roles
 197 throughout this process, as discussed in Mumpower et al. [23]. Once the MDN has been trained on data,
 198 the results are assembled into predictions by sampling the posterior distribution several thousand times.
 199 The final output is a prediction of the mean value of the expected mass, M , and its associated uncertainty,
 200 $\sigma(M)$ for any provided nucleus defined by (Z, N) .

3 RESULTS

201 In this section we present a MDN model trained on hybrid data. We analyze the performance with known
 202 data and discern the ability to extrapolate model predictions. We evaluate the impact of including theoretical
 203 data and the physics-based loss function.

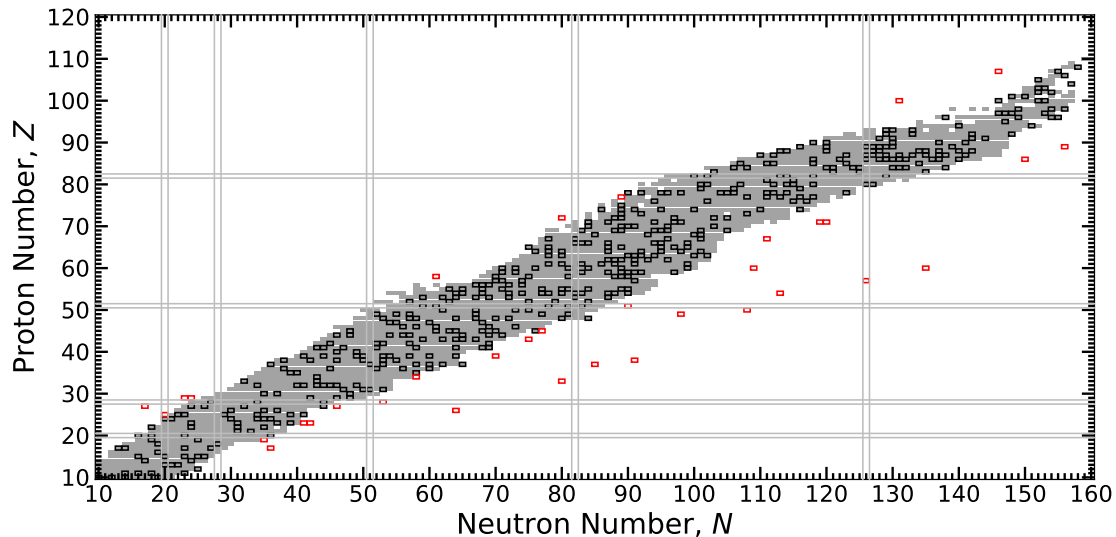


Figure 2. The chart of nuclides showing the extent of the 2020 Atomic Mass Evaluation (AME) indicated by grey squares, training nuclei part of the AME indicated by black squares, and the extra theoretical nuclei indicated by red squares. Closed proton and neutron shells are indicated by parallel lines.

204 3.1 Comparison with existing data

205 The final match to 506 training nuclei for our MDN model is $\sigma_{\text{RMS}} = 0.279$ MeV. The total σ_{RMS} for the
 206 entire AME2020 is 0.395 MeV. This is an increase of roughly 0.116 MeV between training and verification
 207 data which is on the order of the accuracy of the GK relations. We limit these calculations to nuclei with
 208 $A \geq 50$. While the model can predict masses for nuclei lighter than $A = 50$, it generally performs worse in
 209 this region because there are fewer nuclei at lower mass numbers than in heavier mass regions. Therefore,
 210 there are fewer light nuclei selected in the random sample than heavy nuclei.

211 The absolute value of the mass residual, $\Delta M_{Z,N} = |M_{Z,N}^{\text{AME}} - M_{Z,N}^{\text{MDN}}|$, is one way to measure model
 212 performance. Figure 3 plots this quantity across the chart of nuclides versus the AME2020. The predictions
 213 of light nuclei tend to have an error on the order of several MeV with heavier nuclei around 0.3 MeV. The
 214 MDN model performance is on par with commonly used models in the literature.

215 In comparison to our previous results discussed in Mumpower et al. [23], the addition of light nuclei
 216 in training is found to relatively increase the discrepancy for heavier nuclei. The additional information
 217 modestly reduces the overall model quality as measured by σ_{RMS} . On the other hand, the model is better
 218 positioned to describe the nuclear landscape more completely, insofar as the training process introduces
 219 information on the nuclear interaction that is uniquely captured in low-mass systems.

220 The behavior of the model with respect to select isotopic chains are shown in Figure 4. In regions of
 221 the chart where the MDN model is confident in its predictions such as in the $Z = 79$ isotopic chain, the
 222 uncertainties are very well constrained. The converse is also true, as is the case with higher uncertainties
 223 along the $Z = 43$ isotopic chain. The tin ($Z = 50$) isotopic chain highlights an intermediate case.

224 Inspection of this figure shows that the model has a preference for evaluated data in this region and does
 225 not follow the trends of HFB32, despite HFB32 masses being provided for training. This result reveals
 226 a unique feature of our modeling: evaluated data, due to its low uncertainties, is highly favored while
 227 theoretical points, with relatively larger uncertainties, are used as guideposts for how nuclei behave where

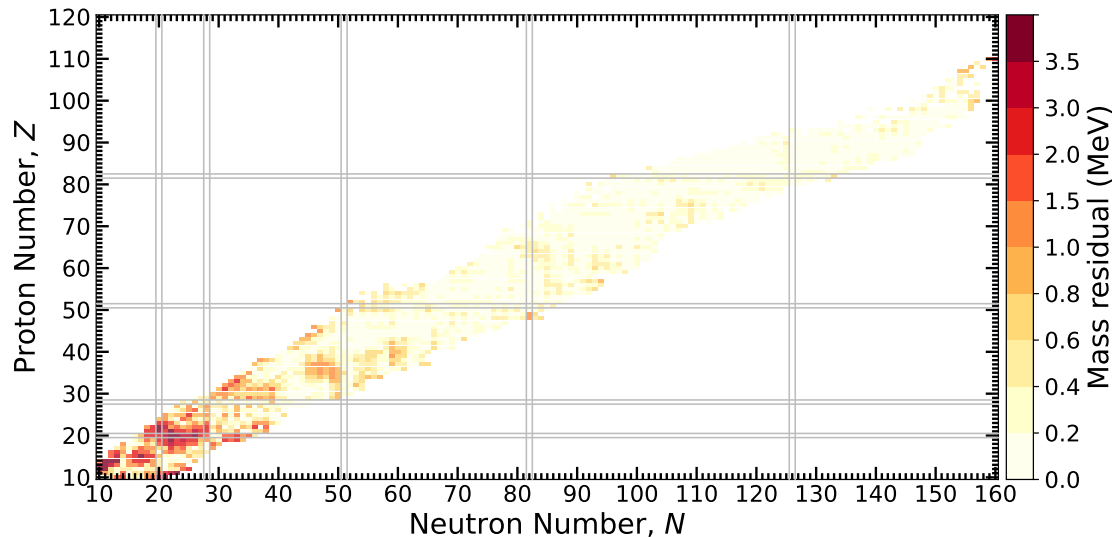


Figure 3. The absolute value of mass residuals across the chart of nuclides using an MDN model and the AME2020. Heavier nuclei are generally well described by the model while lighter nuclei exhibit larger discrepancies. See text for details.

228 there is no data. How much a particularly model is favored farther from stability depends on how much
 229 weighting we provide it with the choice of model uncertainty. The trends of the MDN predictions are
 230 discussed in the next section.

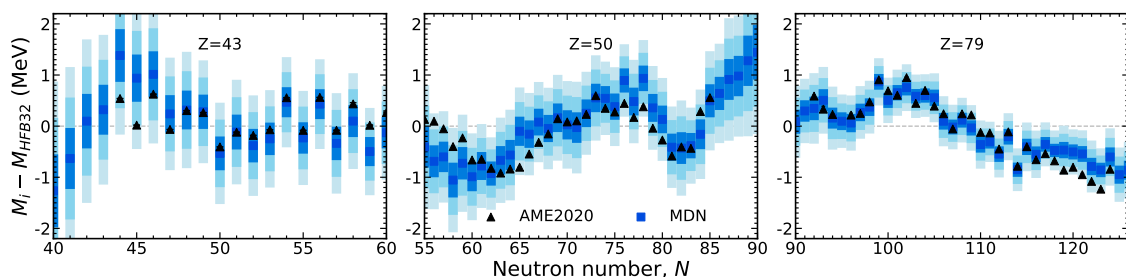


Figure 4. The prediction of masses along three isotopic chains in comparison to AME2020 data. Masses are plotted in reference to HFB32. The MDN model captures the trends exhibited in data and furnishes individual uncertainties (the one, two, and, three sigma confidence intervals are shown by blue shading).

231 3.2 Trends away from measured data

232 The extrapolation quality of atomic mass predictions is an important problem, especially for astrophysical
 233 applications where this information is needed for thousands of unmeasured species [41, 42]. The formation
 234 of the elements in particular requires robust predictions with well-quantified uncertainties [43]. The MDN
 235 supplies such information, and we now gauge the quality of the extrapolations by comparison with other
 236 theoretical models.

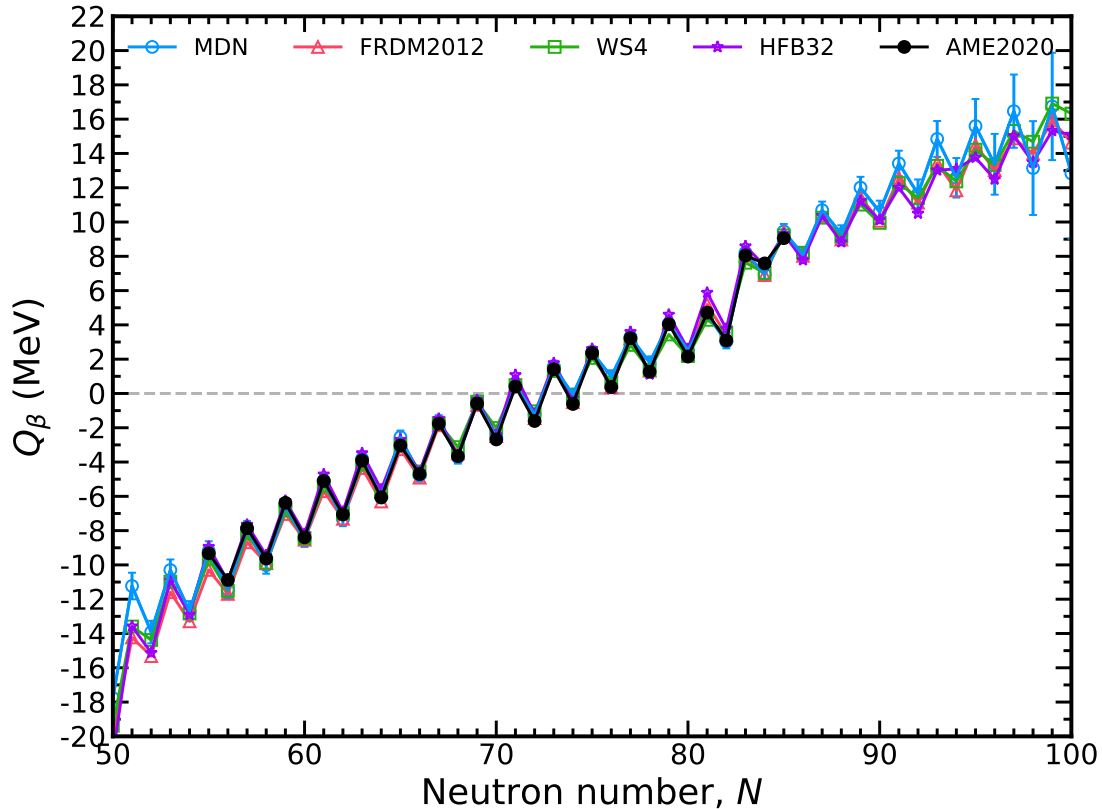


Figure 5. The total available energy for nuclear β^- decay, Q_β , along the tin isotopic chain ($Z = 50$) with a $1-\sigma$ confidence interval. The MDN model (blue) reproduces known data (black) and continues reasonably physical behavior when extrapolating. Theoretical models used in training are plotted for comparison.

237 The $Q_\beta(Z, N) = M_{Z,N} - M_{Z+1,N-1}$ is plotted in Figure 5 for the tin ($Z = 50$) isotopic chain.
 238 Additionally plotted is the uncertainty, δQ_β , which is calculated via propagation of error

$$\delta Q_\beta(Z, N) = \sqrt{\sigma^2(M_{Z,N}) + \sigma^2(M_{Z+1,N-1}) - 2\sigma(M_{Z,N}, M_{Z+1,N-1})}. \quad (11)$$

239 The mass uncertainties $\sigma(M_{Z,N})$, $\sigma(M_{Z+1,N-1})$ are outputs of the MDN. The correlation between the
 240 masses, $\sigma(M_{Z,N}, M_{Z+1,N-1})$, is assumed to be zero. The model has excellent performance where data is
 241 known and this result can be considered representative for other isotopic chains. Predicted uncertainties
 242 grow with decreasing and increasing neutron number outside of measured data, underscoring the Bayesian
 243 nature of our approach.

244 Also shown in Figure 5 are the theoretical models used in training. Comparison with these models shows
 245 that the MDN continues to retain physical behavior when extrapolating to neutron deficient or neutron
 246 rich regions. Intriguingly, the MDN model does not preferentially follow one specific model when extrapolating.
 247 Instead, where there begins to be discrepancies among the theoretical models, the uncertainties begin
 248 to increase. For Q_β , the predictions along the tin isotopic chain begin to be dominated by uncertainties
 249 roughly ten units from the last available AME2020 data point.

250 In Figure 6 we show the extrapolation quality of one-neutron separation energies, $S_{1n}(Z, N) = M_n +$
 251 $M_{Z,N-1} - M_{Z,N}$. The propagation of error formula, Eqn. 11, is again employed to calculate δS_{1n} since

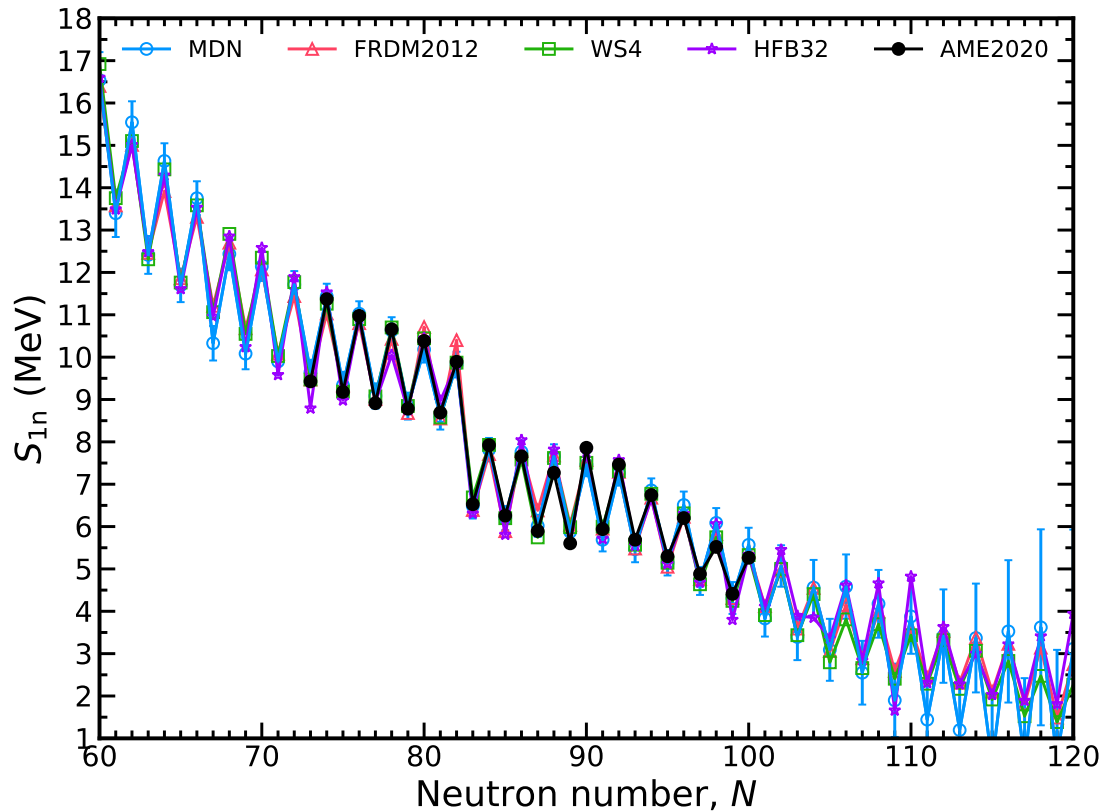


Figure 6. The one-neutron separation energy, S_{1n} , along the promethium isotopic chain ($Z = 61$) with a $1-\sigma$ confidence interval. The MDN model (blue) reproduces known data (black) and continues reasonably physical behavior when extrapolating. Theoretical models used in training are plotted for comparison.

252 this quantity also depends on mass differences. The uncertainty of the mass of the neutron, M_n , can be
 253 safely ignored. The qualitative behavior of S_{1n} is well described. No unphysical inversions of S_{1n} are
 254 found with the MDN model in contrast to the HFB32 model where this behavior can arise; observe around
 255 $N = 105$. Again, we find that roughly ten units from the last measured isotope, uncertainties begin to rise
 256 substantially.

257 A consequence of the growth of uncertainties is that the prediction of the neutron dripline, $S_{1n} = 0$ is also
 258 largely uncertain for any isotopic chain. We conclude that hybrid data does not presently place stringent
 259 constraints on this quantity, which is widely recognized as an open problem by the community [44, 45, 46].

260 Another quantity that can be used to gauge the quality of extrapolations is the two-neutron separation
 261 energy, $S_{2n}(Z, N) = 2M_n + M_{Z, N-2} - M_{Z, N}$. The two-neutron separation exhibits less odd-even
 262 staggering than S_{1n} because the subtraction always pairs even- N or odd- N nuclei. The behavior of the
 263 MDN model is shown in Figure 7 for the lutetium ($Z = 71$), tungsten ($Z = 74$), iridium ($Z = 77$), and
 264 mercury ($Z = 80$) isotopic chains. All experimental data falls within the $1-\sigma$ confidence intervals except
 265 for ^{206}Hg . A relatively robust shell closure is predicted at $N = 126$, though there is some weakening at the
 266 smaller proton numbers.

267 Finally, we consider the behavior of the physics of ground-state masses across the nuclear chart using
 268 the predictions of the MDN model. Whether or not the GK relations are preserved is yet another test of
 269 the extrapolation quality of the MDN. The calculation of the left hand side of Eqns. 6 and 7 is shown in

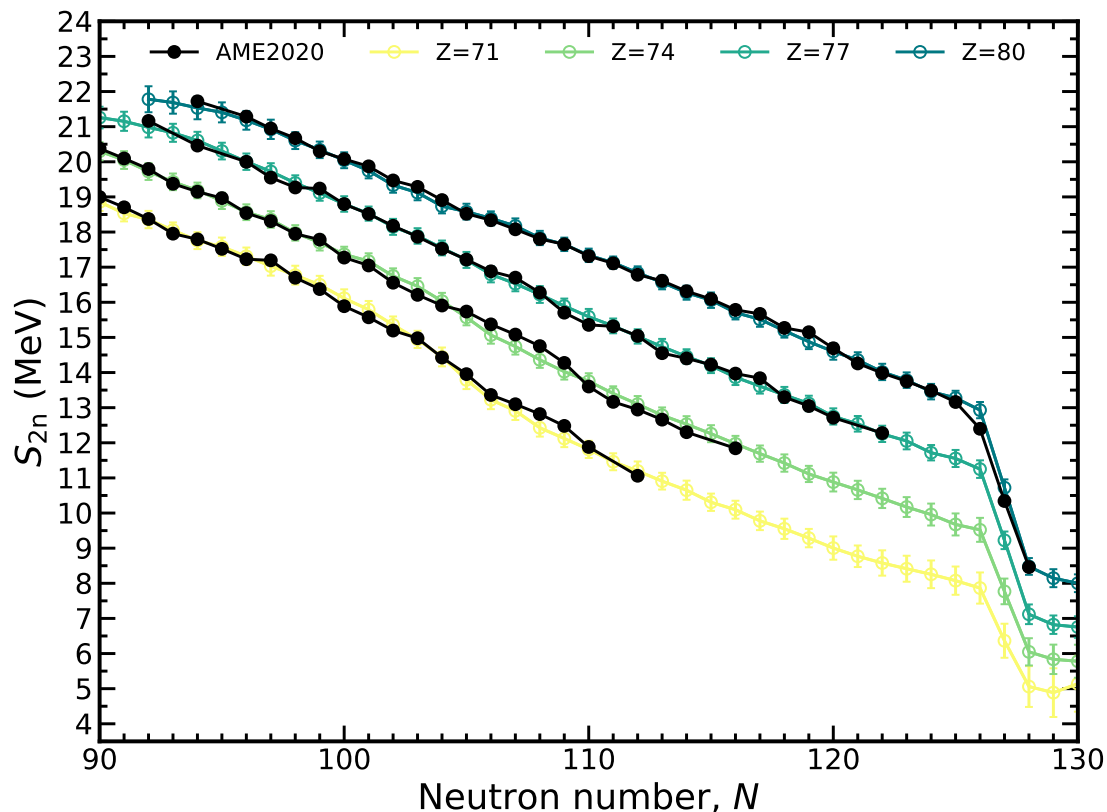


Figure 7. The two-neutron separation energy, S_{2n} , along several isotopic chains plotted with a $1\text{-}\sigma$ confidence interval. The MDN model (colors) reproduces known data (black) and continues reasonably physical behavior when extrapolating.

270 Figure 8 across the chart of nuclides. Yellow shading indicates the GK relations are satisfied while orange
 271 and red shading indicate potential problem areas where the relations have broken down. Given the behavior
 272 seen in the previous figures, it is clear that towards the neutron dripline, the uncertainties have grown so
 273 large that the model is unsure of the preservation of the GK relations. To emphasize this point, we calculate
 274 the nuclei for which the mass uncertainty, δM , is larger than the one-neutron separation energy, S_{1n} , and
 275 designate this as a region bound in black. We observe that this bounded region is precisely where the
 276 orange and red regions are located. Figure 8 suggests that a potential modification of the loss function that
 277 encodes the GK relations could be made to include uncertainties obtained from the MDN. This line of
 278 reasoning is the subject of future work.

279 3.3 Impact of theoretical data and physics constraint

280 We now assess the impact of the inclusion of theoretical data and the physics loss on the predictive
 281 capabilities of the MDN. Figure 9 shows four different training sets in the context of S_{1n} values. The line
 282 labeled MDN is the network shown throughout this manuscript that includes both hybrid data and physical
 283 constraint. A1 is a MDN model trained only with experimental data, lacking information about theory or
 284 the physical loss defined by the GK relations; A2 is a MDN model trained with the physics loss but without
 285 theoretical data; and A3 is a MDN model trained with theory data but without any physics loss.

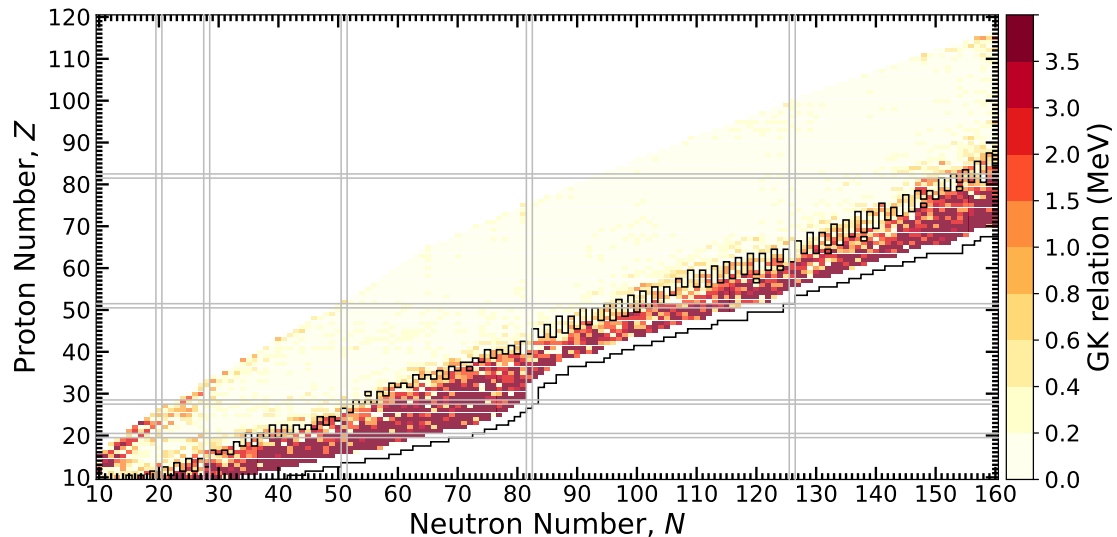


Figure 8. A test of how well the GK relations are maintained throughout the chart of nuclides. Lower values indicate predictions inline with GK, which is found nearly everywhere, except for the most extreme cases where the model is uncertain at the limits of bound nuclei. The black outlined nuclei have $\delta M > S_{1n}$, indicating where mass uncertainties are large.

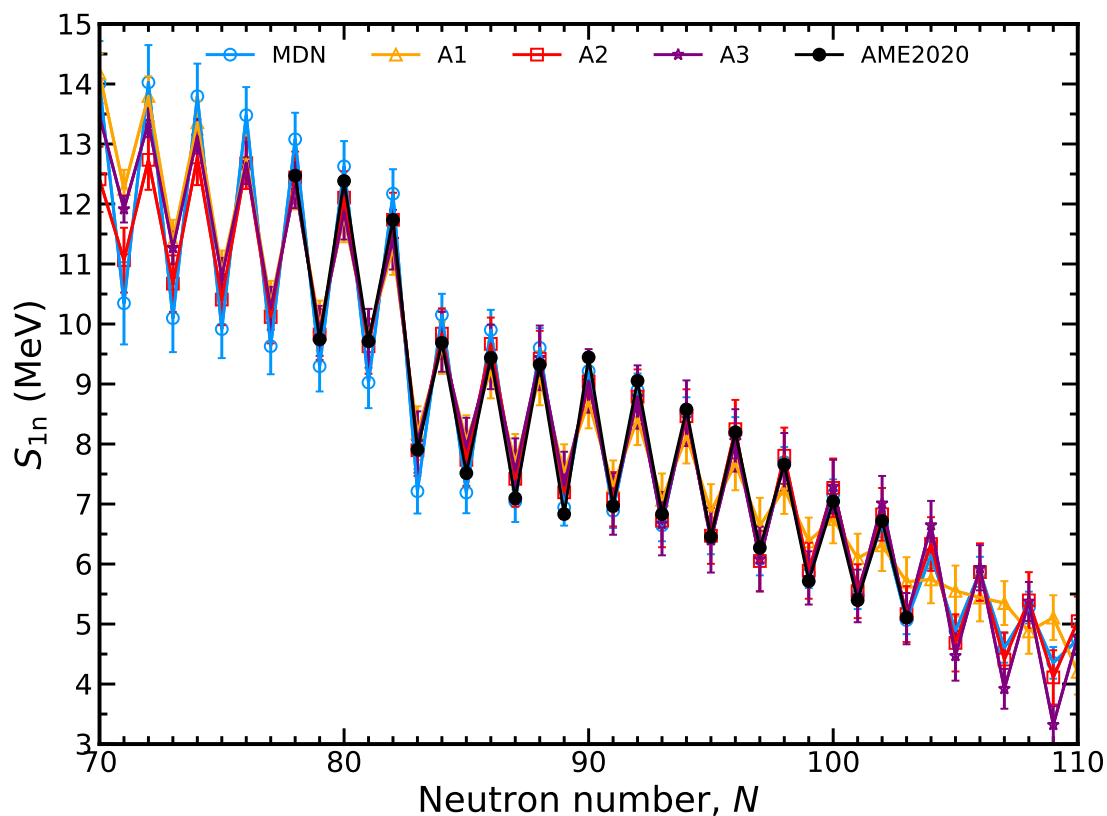


Figure 9. Comparison of MDN models with different assumptions for input data and training loss along the dysprosium ($Z = 66$) isotopic chain. See text for details.

Table 2. The parameters found using a least-square fit of Eqn. 12 to the MDN uncertainties across the chart of nuclides.

| p_0 | p_1 | p_2 | p_3 | p_4 | p_5 |
|-------------------------|-------------------------|-------------------------|-------------------------|------------------------|---------------------|
| -7.035×10^{-1} | -1.037×10^{-1} | -2.997×10^{-3} | -3.729×10^{-4} | 8.782×10^{-7} | 1.109×10^0 |

286 From these four sets, it is clear that both hybrid data *and* the physics-based loss are necessary to provide
 287 quality extrapolations into unknown regions. Training with the lack of theory and GK (A1) exhibits a
 288 less desirable preference for a smooth extrapolation of S_{1n} values. The addition of the physics loss (A2)
 289 improves the situation by restoring the odd-even behavior observed in measured nuclei. The expected
 290 behavior in S_{1n} is also restored by run A3, where the hybrid data includes theory but training is not
 291 informed of the GK relations.

292 We note that the improvement in extrapolation behavior resulting from the hybrid data and physics-based
 293 loss is generally independent of any hyperparameters that otherwise appear in the MDN. In particular, we
 294 have preliminarily verified this result against systematic variations in relevant hyperparameters, including
 295 network size, training size, different nuclei, different input features and different blends of theoretical
 296 models. All of these variations demonstrate a similar propensity for improvement when both physics loss
 297 *and* hybrid data are used. These results lead us to reaffirm our previous observation that the addition of
 298 theory data serves as guideposts for the network solutions while the GK relations are used to ensure a
 299 refined solution.

300 3.4 Estimated growth of uncertainties with neutron number

301 The behavior of mass uncertainties as one traverses the chart of nuclides can be ascertained using the
 302 MDN predictions. Here we consider the evolution of uncertainties provided by an MDN model as a function
 303 of neutron excess, δN . We take the definition of δN to mean the number of neutrons from the last stable
 304 isotope and use the NuBase (2020) data to make this determination [47]. For each isotopic chain, δN may
 305 reference a slightly different neutron number for the particular isotope. The choice of this variable provides
 306 a relatively straight forward way to observe how mass uncertainties grow far from known data. The average
 307 and standard deviation of the MDN model's uncertainties are shown in Fig. 10.

308 The functional form of the average uncertainty growth as a function of neutron excess is well approximated
 309 by the following relation,

$$\sigma(\delta N) \approx p_0 + p_1\delta N + p_2\delta N^2 + p_3\delta N^3 + p_4\delta N^4 + p_5^{\delta N}, \quad (12)$$

310 where the parameters, p_i , are fit numerically (least squares) and are given in Table 2. This functional form
 311 may be readily used in simulations of nucleosynthesis to approximate uncertainties in masses with models
 312 that do not provide this information.

4 CONCLUSION

313 We present a Bayesian averaging technique that can be used to study the ground-state masses of atomic
 314 nuclei with corresponding uncertainties. In this work, we combine high-precision evaluated data, weighted
 315 strongly, with theoretical data for nuclei which are further from stability, more poorly understood, and
 316 therefore weighted more weakly. Training of a probabilistic neural network is used to construct the
 317 posterior distribution of ground-state masses. Along with a loss function for matching data, a second,
 318 physics-based loss function is employed in training to emphasize the relevant local behavior of masses.

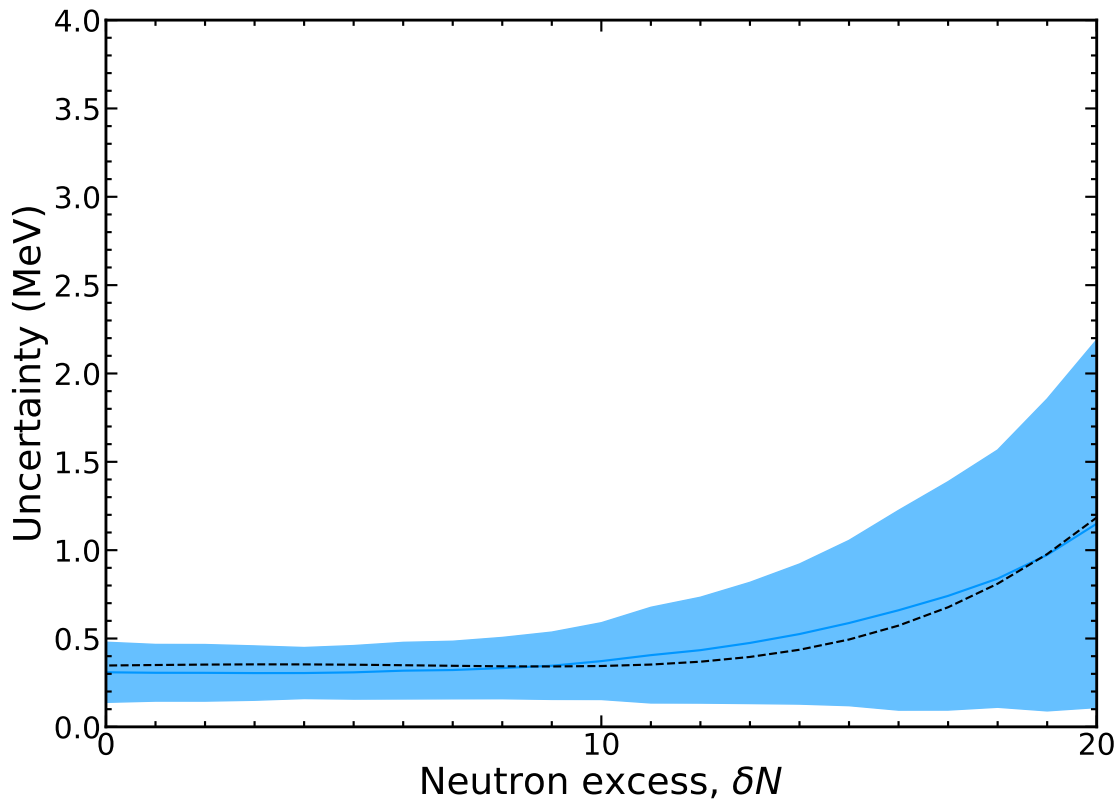


Figure 10. The average and standard deviation of the growth of mass uncertainties as a function of neutron excess. The functional form of the average can be well modeled by Eqn. 12 as plotted with a dashed black line.

319 Excellent performance is obtained with comparison to known data, on the order of $\sigma_{\text{RMS}} \sim 0.3$ MeV, and
320 the physical behavior of solutions is maintained when extrapolating. It is found that available data from
321 experiment and theory are not, at this time, sufficient to resolve the relatively large uncertainties towards
322 the limits of bound nuclei using the framework developed in this work. We emphasize the continuing need
323 for advances in nuclear experiment and theory to reduce these uncertainties.

324 Our Bayesian averaging procedure enables the rapid construction of a mass model using any combination
325 of precise and imprecise data through adjustable stochastic weights of the hybrid training inputs. For
326 instance, if a particular theoretical model is favored over another, its sampling can be adjusted accordingly
327 to emphasize its importance. Similarly, new high-precision data may be incorporated in the future from
328 measurement campaigns at radioactive beam facilities. At the same time, our technique also enables
329 freedom in the exploration of the relevant physics of ground-state masses. This can be achieved by probing
330 a variety of physics-based features, for example, or by introducing alternative physics-based loss functions
331 in training.

332 The methodology outlined here can be generalized to describe any nuclear physics property of interest,
333 particularly when reliable extrapolations are necessary. This technique opens new avenues into Machine
334 Learning research in the context of nuclear physics through the unification of data, theory, and associated
335 physical constraints to empower predictions with quantified uncertainties. We look forward to extensions
336 of this work to model nuclear decay properties, such as half-lives and branching ratios, as particularly
337 promising opportunities in the near future.

CONFLICT OF INTEREST STATEMENT

338 The authors declare that the research was conducted in the absence of any commercial or financial
339 relationships that could be construed as a potential conflict of interest.

AUTHOR CONTRIBUTIONS

340 M. R. Mumpower led the study, overseeing all aspects of the project, including writing the code used in this
341 study. M. Li ran and analyzed combinations of hybrid input data as well as hyperparameters. T. M. Sprouse,
342 A. E. Lovell, and A. T. Mohan provided technical expertise for Machine Learning methods. All authors
343 contributed to the writing of the manuscript, and read and approved the submitted version.

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DATA AVAILABILITY STATEMENT

351 The raw data supporting the conclusions of this article will be made available by the authors, without undue
352 reservation.

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